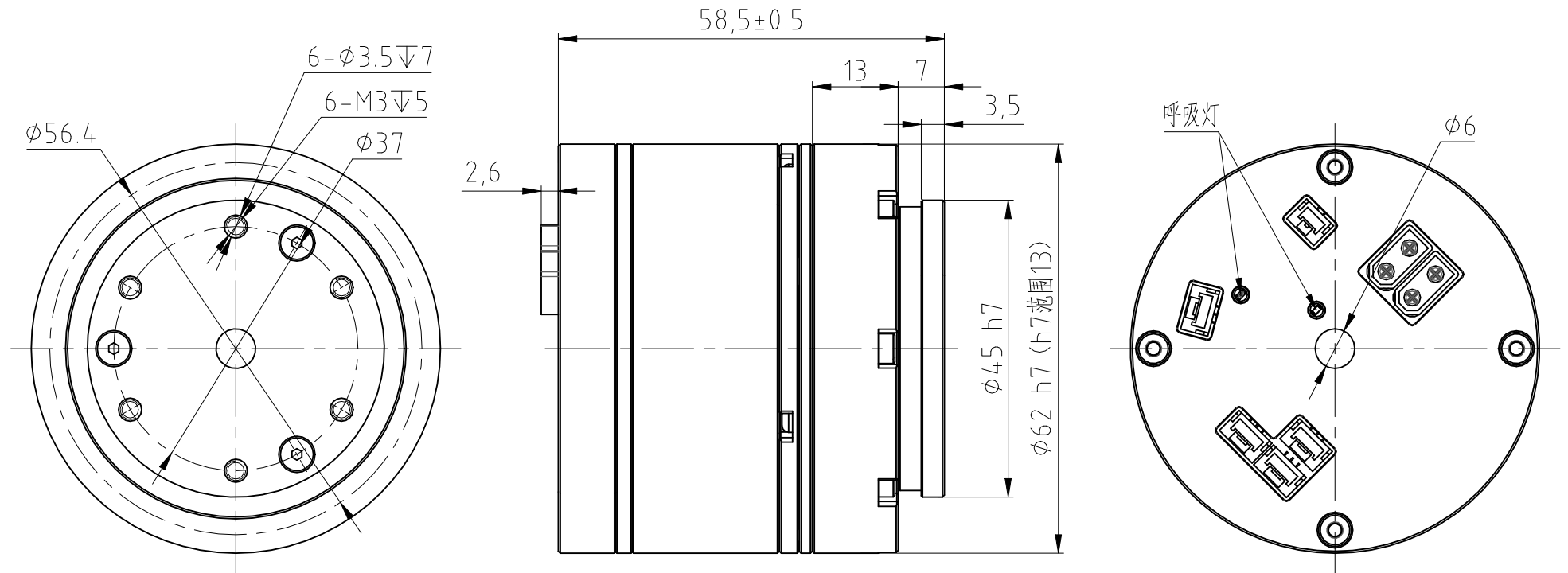
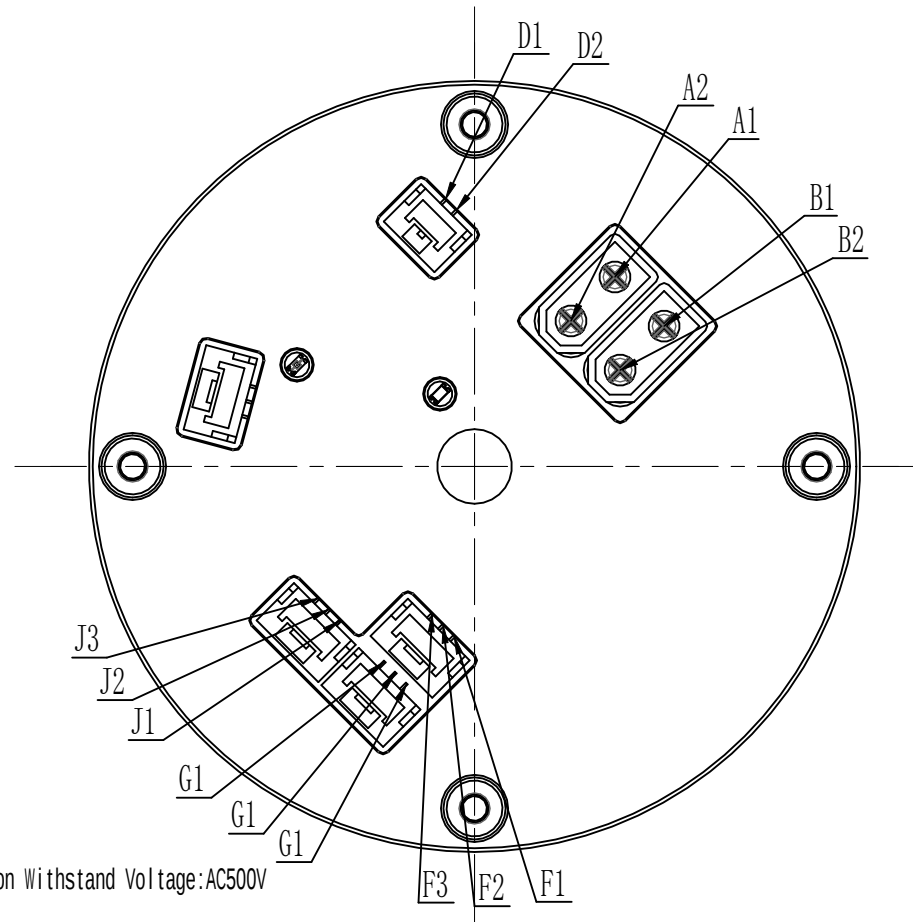


客户会签



						Rotary Actuator			L62I-C-XXX-BF-C00
									GJ-DW-ME-0055
标记	处数	更改内容	签字	日期		客户图样标记	重量(kg)	比例	Laitual Drive 浙江来福谐波传动股份有限公司
设计								1:1	
审核									
批准									
工艺会签									
				版本号	A1	共 2 页	第 1 页		



Technical Requirements:

1. Insulation Resistance(DC500V)>500M Ω ; Insulation Withstand Voltage:AC500V (1minute), Less than 5mA ;
2. Motor-side Encoder Resolution:16-bit multi-turn,17-bit single-turn ;
Reducer-side Encoder Resolution:17-bit single-turn(Optional,not configured by default for standard products) ;
3. Bus Protocol:Canopen ;
4. Appearance:No visible burrs,scratches,bumps or other defects ;
5. Storage temperature for standard products:-20~80,Operating temperature:-10~55 ; Storage temperature for special products:-40~80,Operating temperature:-30~55 ;
6. Unidirectional positioning accuracy:60 Arcsec, Repetitive positioning accuracy:20Arcsec.

Module Signal Definition

Pin No.	Signal Name	Remarks
A1/B1	VBUS+	Bus Power Input/Output Positive
A2/B2	VBUS-	Bus Power Input/Output Negative
D1	BAT+	Multi-turn Encoder Backup Battery Positive
D2	BAT-	Multi-turn Encoder Backup Battery Negative
F1/G1	CAN_H	CAN Bus High Signal
F2/G2	CAN_GND	CAN Bus Ground
F3/G3	CAN_L	CAN Bus Low Signal
J1/K1	RS485_A	RS485 Bus A Terminal
J2/K2	RS485_GND	RS485 Bus Ground
J3/K3	RS485_B	RS485 Bus B Terminal

Module Data

Ratio	Ratio Torque (Nm)	Permissible peak torque at start /stop(Nm)	Instantaneous permissible max torque(Nm)	Rated Speed (rpm)	Max. Speed (rpm)	Rated Current (A)	Max. Current (A)	Tq - Constant (Nm/Arms)	Inertia Moment (kg·mm ²)	Weight (kg)
51	5.5	8.3	17	98	117.6	2.44	3.68	2.25	15.5	0.63
—	—	—	—	—	—	—	—	—		
101	8.9	11	25	49.5	59.4	1.99	2.46	4.47		
—	—	—	—	—	—	—	—	—		

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		版本号	A1		

Rotary Actuator

L62I-C-XXX-BF-C00

GJ-DW-ME-0055

客户图样标记	重量(kg)	比例
		1:1
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